## Infotheory for Statistics and Learning Lecture 0

Basic concepts in probability

Mikael Skoglund

Measurable space  $(\Omega, \mathcal{A})$ , with  $\mathcal{A} =$  the class of measurable sets

•  $\mathcal{A}$  is a  $\sigma$ -algebra, i.e.  $A \in \mathcal{A} \Rightarrow A^c \in \mathcal{A}$  and  $A_i \in \mathcal{A} \Rightarrow \cup_i A_i \in \mathcal{A}$ 

Measure space  $(\Omega, \mathcal{A}, \mu)$  with  $\mu(A)$  the measure of  $A \in \mathcal{A}$ 

Class of Borel sets on  $\mathbb{R}$  = smallest  $\sigma$ -algebra that contains the open intervals (all sets of the form (a, b), b > a), notation  $\mathcal{B}(\mathbb{R})$ 

A real-valued function  $f: \Omega \to \mathbb{R}$  is measurable if

$$f^{-1}(B) = \{\omega \in \Omega : f(\omega) \in B\} \in \mathcal{A} \text{ for all } B \in \mathcal{B}$$

For fixed  $n < \infty$ ,  $a_i \in \mathbb{R}$  and  $A_i \in \mathcal{A}$ ,  $i = 1, \ldots, n$ , a measurable function of the form

$$s(x) = \sum_{i=1}^{n} a_i \chi_{A_i}(x)$$

(with  $\chi_A(x) = 1$  if  $x \in A$  and = 0 o.w.) is called a simple function

The integral of a simple function s(x) is defined as

$$\int s(x)d\mu = \sum_{i=1}^{n} a_i \mu(A_i)$$

Any nonnegative measurable function f(x) can be written as  $f(x) = \lim_{i \to \infty} s_i(x)$  where  $\{s_i(x)\}$  is a sequence of nonnegative simple functions such that  $s_1(x) \leq s_2(x) \leq \cdots \leq f(x)$ 

The integral of a nonnegative measurable f is then obtained as

$$\int f(x)d\mu = \lim_{i \to \infty} \int s_i(x)d\mu$$

The integral of a general measurable function is defined as

$$\int f(x)d\mu = \int \max\{f(x), 0\}d\mu - \int (-\min\{f(x), 0\})d\mu$$

A measurable function f is integrable if  $\int |f| d\mu < \infty$ 

Mikael Skoglund

Probability space = a measure space  $(\Omega, \mathcal{A}, P)$  such that  $P(\Omega) = 1$ Random variable = a measurable real-valued function  $X : \Omega \to \mathbb{R}$ Distribution  $P_X$  of X, for  $E \in \mathcal{B}$ ,

$$P_X(E) = P(\{\omega : X(\omega) \in E\})$$

• We get a new probability space  $(\mathbb{R}, \mathcal{B}, P_X)$ 

Probability distribution  $F_X(x)$  of X,

$$F_X(a) = P_X(\{X \le a\}) = P(\{\omega : X(\omega) \le a\})$$

Expectation, for measurable g(x)

$$E[g(X)] = \int_{\mathbb{R}} g(x)dP_X = \int_{\Omega} g(X(\omega))dP$$

X is discrete if there is a countable  $K \in \mathcal{B}$  such that  $P_X(K) = 1$ For a discrete X we define  $p_X(k) = P(\{\omega : X(\omega) = k\}), k \in K$ , the probability mass function (pmf) of X

X is continuous if  $P_X(\{x\}) = 0$  for all  $x \in \mathbb{R}$ 

X is absolutely continuous if there is a function  $f_X(x) \ge 0$  such that

$$P_X(B) = \int_B f_X(x) dx = \int \chi_B(x) f_X(x) dx$$

for all  $B \in \mathcal{B}$ , the probability density function (pdf) of X

Mikael Skoglund

Integration/expectation:

If X is discrete on K

$$E[g(X)] = \int g(x)dP_X = \sum_{k \in K} g(k)p_X(k) = \sum_x g(x)p_X(x)$$

If X is absolutely continuous

$$E[g(X)] = \int g(x)dP_X = \int g(x)f_X(x)dx$$

Assume that P and Q are two probability measures on  $(\Omega, \mathcal{A})$ , and that P(A) = 0 for all  $A \in \mathcal{A}$  where Q(A) = 0, notation  $P \ll Q$ 

Then there exists a measurable function f such that

$$P(B) = \int_B f(\omega) dQ$$

for all  $B \in \mathcal{A}$ 

The function f is called the Radon–Nikodym derivative of P w.r.t. Q, notation

$$f(\omega) = \frac{dP}{dQ}(\omega)$$

Note that f is a random variable

Mikael Skoglund

## On $(\mathbb{R}, \mathcal{B})$ :

For two discrete distributions  $P_X$  and  $Q_X$  with pmfs p and q

$$\frac{dP_X}{dQ_X}(x) = \frac{p(x)}{q(x)}$$

For two absolutely continuous distributions  ${\cal P}_X$  and  ${\cal Q}_X$  with pdfs f and g

$$\frac{dP_X}{dQ_X}(x) = \frac{f(x)}{g(x)}$$

Note that if  $\lambda$  is Lebesgue measure<sup>1</sup> on  $\mathcal{B}$  and  $P_X \ll \lambda$  then

$$P_X(B) = \int_B \frac{dP_X}{d\lambda}(x)d\lambda$$

That is,

$$f_X(x) = \frac{dP_X}{d\lambda}(x)$$

is the pdf of  $P_X$ 

Thus, X is absolutely continuous  $\iff P_X \ll \lambda$ 

 $^{1}$ With a more general definition of R–N derivative, since Lebesgue measure is not a prob. measure Mikael Skoglund