

Infotheory for Statistics and Learning

Lecture 11

- Sparse denoising [PW:30.2]
- Sparse linear regression [PW:30.2],[RWY]
- Compressed sensing [CRT]
- Almost lossless analog compression [WV]

Notation for asymptotic behavior:

$f(n) = \Theta(g(n)) \iff$ there is an $n_0 > 0$ and constants C_1, C_2 such that for all $n > n_0$, $C_1g(n) \leq f(n) \leq C_2g(n)$

$f(n) \lesssim g(n) \iff$ there is an $n_0 > 0$ and a constant C_1 such that for all $n > n_0$, $f(n) \leq C_1g(n)$

$f(n) \gtrsim g(n) \iff$ there is an $n_0 > 0$ and a constant C_2 such that for all $n > n_0$, $f(n) \geq C_2g(n)$

That is, $f(n) = \Theta(g(n)) \iff g(n) \lesssim f(n) \lesssim g(n)$

Sparse Denoising

Consider the GLM, $Y_i = \theta + Z_i$, where $Z_i \sim \mathcal{N}(0, I_p)$, $i = 1, \dots, n$ i.i.d. and $\theta \in \mathbb{R}^p$

Assume θ is **sparse** in the sense $\|\theta\|_0 \leq k < p$, $\|\theta\|_0 = |\{i : \theta_i \neq 0\}|$

Let $T_k = \{\theta : \|\theta\|_0 \leq k\}$ and consider the minimax risk for $\ell(\theta, \hat{\theta}) = \|\theta - \hat{\theta}\|^2$ and $n = 1$

$$R_1^*(T_k) = \inf_{\hat{\theta}} \sup_{\theta \in T_k} E_{\theta}[\|\theta - \hat{\theta}(Y)\|^2]$$

where E_{θ} denotes expectation over $Y = \theta + Z \sim \mathcal{N}(\theta, I_p)$

For $n > 1$ we get

$$R_n^*(T_k) = \frac{1}{n} R_1^*(T_k)$$

because $\bar{Y} = n^{-1} \sum_i Y_i$ is a sufficient statistic

Lower bound on $R^*(T_k) = R_1^*(T_k)$:

Since $R_{\pi}^* \leq R^*$ (Bayesian \leq minimax) for any prior π on θ , we can choose π by drawing b uniformly from $\{b \in \{0, 1\}^p : \|b\|_0 = k\}$ and setting $\theta = \tau b$ for some $\tau > 0 \Rightarrow b \rightarrow \theta \rightarrow Y \rightarrow \hat{\theta} \rightarrow \hat{b}$

We have

$$I(\theta; \hat{\theta}) \leq \sup_{\pi} I(\theta; Y) \leq \sup_{\theta \neq \theta'} D(\mathcal{N}(\theta, I_p) \parallel \mathcal{N}(\theta', I_p)) \leq k\tau^2$$

Assume we use $\hat{b} = \min \|\hat{\theta} - \tau b\|_0$ over $\{b \in \{0, 1\}^p : \|b\|_0 = k\}$, then $\tau^2 \|b - \hat{b}\|_0 \leq 4\|\theta - \hat{\theta}\|^2 \Rightarrow \tau^2 E[\|b - \hat{b}\|_0] \leq 4R^*$

Thus $I(b; \hat{b}) \geq \min I(b; \hat{b})$ where the min is over distributions on b such that $E[\|b - \hat{b}\|_0] \leq 4R^*/\tau^2$, leading to the bound (in nats)

$$I(b; \hat{b}) \geq \ln \binom{p}{k} - p h \left(\frac{4R^*}{\tau^2 p} \right)$$

where $h(x) = -x \ln x - (1-x) \ln(1-x)$

Since $E[\|\theta - \hat{\theta}\|^2] \leq E[\|\theta\|^2] = k\tau^2$ we can set $R_\pi^* = \varepsilon(k)k\tau^2$ with $\varepsilon(k) \in (0, 1)$, and since $I(b; \hat{b}) \leq I(\theta; \hat{\theta})$ we get

$$\ln \binom{p}{k} - p h \left(\frac{4\varepsilon(k)k}{p} \right) \leq \frac{R_\pi^*}{\varepsilon(k)} \leq \frac{R^*}{\varepsilon(k)}$$

Now assume $k = k(p) \rightarrow \infty$ as $p \rightarrow \infty$. Then Stirling \Rightarrow

$$\ln \binom{p}{k} \approx \frac{1}{2} \ln \frac{p}{k(p-k)2\pi} + p h \left(\frac{k}{p} \right)$$

Assuming $\varepsilon_0 < \varepsilon(k) < (1 - \varepsilon_0)/4$, for some $0 < \varepsilon_0 \ll 1$, and $k/p < 1/2 \Rightarrow$

$$\begin{aligned} R^* &> \varepsilon_0 \left[\frac{1}{2} \ln \frac{p}{k(p-k)2\pi} + p h \left(\frac{k}{p} \right) - p h \left(\frac{(1 - \varepsilon_0)k}{p} \right) \right] \\ &\gtrsim p h \left(\frac{k}{p} \right) \gtrsim k \ln \frac{p}{k} \end{aligned}$$

Upper bound on $R^*(T_k)$

For $Y = \theta + Z$ we study $\hat{\theta} = \arg \min_{\theta \in T_k} \|Y - \theta\|^2$

We get (with $\cdot =$ scalar product)

$$\|Z - (\hat{\theta} - \theta)\|^2 \leq \|Y - \theta\|^2 = \|Z\|^2 \Rightarrow \|\theta - \hat{\theta}\|^2 \leq 2(\theta - \hat{\theta}) \cdot Z$$

Consequently, since also $\|\theta - \hat{\theta}\|_0 \leq 2k$,

$$\frac{1}{2} \|\theta - \hat{\theta}\| \leq \sup_{u \in S^p \cap T_{2k}} Z \cdot u = \max_{|J|=2k} \|Z_J\|$$

where $S^p =$ the unit sphere in \mathbb{R}^p , Z_J the sub-vector defined by J

Because $Z \sim \mathcal{N}(0, I_p)$, it can now be shown that

$$\Pr \left(\|Z_J\|^2 \geq k \ln \frac{pe}{k} \right) \leq \exp \left(-\frac{ck}{2} \ln \frac{p}{k} \right)$$

\Rightarrow for $\ell = k \ln(p/k)$ and $\varepsilon > 0$, there is an L such that for $\ell > L$

$$\Pr\left(\|Z_J\|^2 \geq k \ln \frac{pe}{k}\right) \leq \varepsilon$$

Hence for large ℓ

$$E[\|\theta - \hat{\theta}\|^2] \leq 4k \ln \frac{pe}{k} = \Theta\left(k \ln \frac{p}{k}\right)$$

That is,

$$R^* \lesssim k \ln \frac{p}{k}$$

Consequently

$$R^* = \Theta\left(k \ln \frac{p}{k}\right)$$

Sparse Linear Regression

$Y = X\theta + Z$, $Y \in \mathbb{R}^{n \times 1}$, $\theta \in T_k \subset \mathbb{R}^{p \times 1}$, $n \geq p$, $k < p$,

$X_{ij} \sim \mathcal{N}(0, 1/n)$ and independent; $Z \sim \mathcal{N}(0, I_n)$

For $\hat{\theta} = \hat{\theta}(X, Y)$ the minimax risk is

$$R^* = R_n^*(T_k) = \inf_{\hat{\theta}} \sup_{\theta \in T_k} E_{\theta} \|\theta - \hat{\theta}(X, Y)\|^2$$

with E_{θ} over X and $Y \sim \mathcal{N}(0, (\|\theta\|^2/n + 1)I_n)$

Bounding $I(\theta; \hat{\theta})$ it can be shown that

$$R^* \gtrsim k \ln \frac{p}{k}$$

for any n ; i.e. the same lower bound as for $n = p$ and $X = I_p$

To get an upper bound, consider $\hat{\theta} = \arg \min_{\theta \in T_k} \|Y - X\theta\|^2$

$$\Rightarrow \|X(\theta - \hat{\theta})\|^2 \leq 2\|\theta - \hat{\theta}\| \sup_{u \in S^p \cap T_{2k}} Z \cdot (Xu)$$

For $J = \{i : (\theta - \hat{\theta})_i \neq 0\}$, let X_J be the corresponding part of X

Then with $v = \theta - \hat{\theta}$

$$\inf_{v \in T_{2k}} \frac{\|Xv\|}{\|v\|} = \min_{|J| \leq 2k} \sigma_{\min}(X_J)$$

where $\sigma_{\min}(X_J)$ is the smallest singular value of X_J

For $\ell = k \ln(p/k)$, $\Pr(\min_{|J| \leq 2k} \sigma_{\min}(X_J) < 1/2) \rightarrow 0$ as $\ell \rightarrow \infty$

$\Rightarrow \|\theta - \hat{\theta}\| < 2\|X(\theta - \hat{\theta})\|$ with high prob. as $\ell \rightarrow \infty$

Now, similarly as for $n = p$ and $X = I_p$, we can show that

$$\sup_{u \in S^p \cap T_{2k}} Z \cdot (Xu) \lesssim \sqrt{k \ln \frac{ep}{k}}$$

with high probability, so overall we have

$$R^* \lesssim k \ln \frac{p}{k}$$

Compressed Sensing

Consider $y = X\theta + z$, $y \in \mathbb{R}^{n \times 1}$, $\theta \in T_k \subset \mathbb{R}^{p \times 1}$, $k < p$ and $n < p$ (or $n \ll p$); the system is seemingly **underdetermined**, but $\theta \in T_k$

The elements of y are **linearly compressed measurements** of θ , disturbed by z

All variables are deterministic and it is known that $\|z\| \leq \varepsilon$

For $\varepsilon = 0$ a brute force approach to recovering θ from y is to try to solve all possible systems $y = X_J\theta_J$ for all J s.t. $|J| \leq k$

\Rightarrow an integer program of exponential complexity

However, it turns out that we can instead solve the convex program

$$\min \|\theta\|_1 \quad \text{s.t.} \quad X\theta = y$$

where $\|\theta\|_1 = \sum |\theta_i|$. Let $\tilde{\theta}$ denote the solution

Uniform uncertainty or restricted isometry:

Define $\delta_k = \delta_k(X)$ as the smallest $\delta > 0$ such that

$$(1 - \delta)\|b\|^2 \leq \|X_J b\|^2 \leq (1 + \delta)\|b\|^2$$

for all $J \subset \{1, \dots, p\}$, $|J| \leq k$, and $b \in \mathbb{R}^{|J|}$

For $\varepsilon = 0$, it has been shown¹ that $\tilde{\theta} = \theta$ as long as X fulfills

$$\delta_k + \delta_{2k} + \delta_{3k} < 1$$

In the case $\varepsilon > 0$ we can instead solve the convex program

$$\min \|\theta\|_1 \quad \text{s.t.} \quad \|X\theta - y\| \leq \varepsilon$$

Let $\hat{\theta}$ denote the solution

¹Candès & Tao, "Decoding by linear programming," *IEEE Trans. IT*, Dec. 2005

We have the following result (see [CRT]):

As long as $\delta_{3k} + 3\delta_{4k} < 2$, $\hat{\theta}$ fulfills

$$\|\hat{\theta} - \theta\| \leq C(\delta_{4k})\varepsilon$$

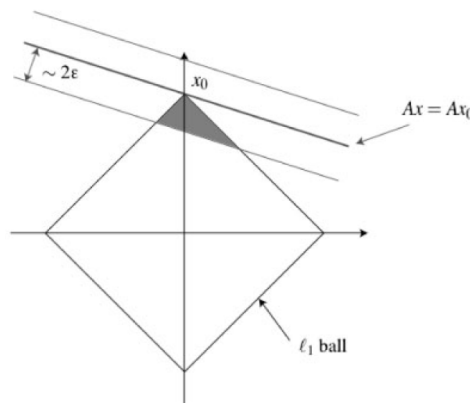


FIGURE 2.1. Geometry in \mathbb{R}^2 . Here, the point x_0 is a vertex of the ℓ_1 -ball, and the shaded area represents the set of points obeying both the tube and the cone constraints. By showing that every vector in the cone of descent at x_0 is approximately orthogonal to the null space of A , we will ensure that x^\sharp is not too far from x_0 .

Illustration from [CRT]

$\hat{\theta} = \theta + h \Rightarrow \|Xh\| \leq 2\varepsilon$ and $\|h_{J^c}\|_1 \leq \|h_J\|_1$, $J = \text{support of } \theta$, $|J| \leq k$
 Restricted isometry $\Rightarrow \|Xh\| \approx \|h\|$

Almost Lossless Analog Compression

In compressed sensing we had **linear** encoding = dimensionality reduction, $p \rightarrow n$

The general case (stochastic setting): Consider a stochastic process $\{X_i\}$ with $X_i \in \mathcal{X}$ for a given measurable space $(\mathcal{X}, \mathcal{F})$

Given another space $(\mathcal{Y}, \mathcal{G})$, an **(n, k) -code** for $\{X_i\}$ is, for each $1 \leq k \leq n < \infty$, defined by

- an encoder $f_n : \mathcal{X}^n \rightarrow \mathcal{Y}^k$
- a decoder $g_n : \mathcal{Y}^k \rightarrow \mathcal{X}^n$

where f_n is measurable in the sense $f_n^{-1}(G) \in \mathcal{F}^n$ for all $G \in \mathcal{G}^k$, and g_n is measurable in the sense $g_n^{-1}(F) \in \mathcal{G}^k$ for all $F \in \mathcal{F}^n$

Let $r(\varepsilon) = \text{infimum of all } r \text{ such that there is a sequence of } (n, \lfloor rn \rfloor)\text{-codes that fulfills}$

$$\limsup_{n \rightarrow \infty} \Pr(g_n(f_n(X^n)) \neq X^n) \leq \varepsilon$$

Assume $\mathcal{X} = \mathcal{Y} = \mathbb{R}$ and $\mathcal{F} = \mathcal{G} = \mathcal{B}$ (the Borel sets), then without further restrictions on (f_n, g_n) we have $r(\varepsilon) = 0$ for all $\varepsilon \in [0, 1]$

... since $(\mathbb{R}^n, \mathcal{B}^n)$ and $(\mathbb{R}, \mathcal{B})$ are Borel equivalent

However the corresponding encoders and decoders are in general highly irregular \Rightarrow hard to describe and non-robust to disturbances

Assume that $\{X_i\}$ is iid with $P_X = \alpha P_c + (1 - \alpha)P_d$ where P_c is abs. continuous and P_d is discrete

Then, with **regularity constraints** we get (see [WV]):

f_n	g_n	$r(\varepsilon)$
linear	general	α
continuous	continuous	0
general	Lipschitz	α

The decoder g_n is Lipschitz \iff for every x and y in \mathbb{R}^k there is an $L < \infty$ such that $\|g_n(x) - g_n(y)\| \leq L\|x - y\|$

Note that imposing that f_n and g_n be continuous does not affect $r(\varepsilon)$ (also note that continuous $\not\iff$ Lipschitz)

A model for [sparsity](#)

$$P_X = \alpha P_c + (1 - \alpha)\delta_0$$

where δ_0 is the Dirac measure, i.e. for $B \in \mathcal{B}$

$$\delta_x(B) = \begin{cases} 1 & x \in B \\ 0 & \text{o.w} \end{cases}$$

Then with linear encoding $r(\varepsilon) = \alpha$