

# Infotheory for Statistics and Learning

## Lecture 4

- Binary hypothesis testing [PW:14],[CT:11.7]
- The Neyman–Pearson lemma [PW:14]
- General theory [PW:28]
- Bayes and minimax [PW:28.3]
- The minimax theorem [PW:28.3]

## Binary Hypothesis Testing

Consider  $P$  and  $Q$  on  $(\Omega, \mathcal{A})$

One of  $P$  and  $Q$  is the correct measure, i.e. the probability space is either  $(\Omega, \mathcal{A}, P)$  or  $(\Omega, \mathcal{A}, Q)$

Based on observation  $\omega$  we wish to decide  $P$  or  $Q$ ,

**hypotheses**  $H_0 : P$  and  $H_1 : Q$

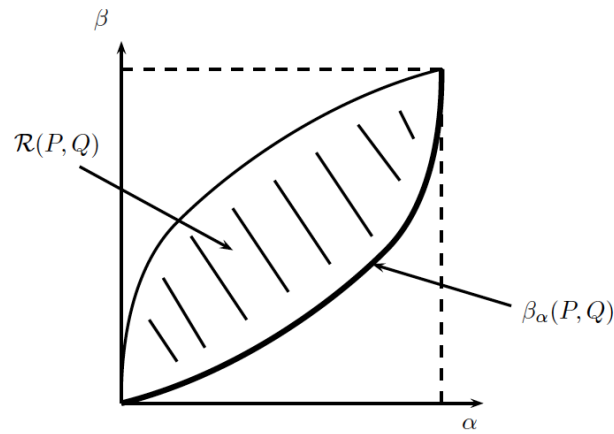
A **decision kernel**  $P_{Z|\omega}$  for  $Z \in \{0, 1\}$ ;  $Z = 0 \rightarrow H_0$ ,  $Z = 1 \rightarrow H_1$

Define  $P_Z = P_{Z|\omega} \circ P$ ,  $Q_Z = P_{Z|\omega} \circ Q$  and

$$\alpha = P_Z(\{0\}), \quad \beta = Q_Z(\{0\}), \quad \pi = Q_Z(\{1\})$$

Tradeoff between  $\alpha$  (correct negative) and  $\beta$  (false negative)

$\pi = 1 - \beta$  power of the test (correct positive)



Define

$$\beta_\alpha(P, Q) = \inf_{P_{Z|\omega}: P_Z(\{0\}) \geq \alpha} Q_Z(\{0\})$$

and

$$\mathcal{R}(P, Q) = \bigcup_{P_{Z|\omega}} \{(\alpha, \beta)\}$$

Note that  $(\alpha, \beta) \in \mathcal{R}(P, Q) \iff (1 - \alpha, 1 - \beta) \in \mathcal{R}(P, Q)$

## Bounds on $\mathcal{R}(P, Q)$

Binary divergence for  $0 \leq x \leq 1$ ,  $0 \leq y \leq 1$ ,

$$d(x||y) = x \log \frac{x}{y} + (1 - x) \log \frac{1 - x}{1 - y}$$

Then if  $(\alpha, \beta) \in \mathcal{R}(P, Q)$

$$d(\alpha||\beta) \leq D(P||Q), \quad d(\beta||\alpha) \leq D(Q||P)$$

Also, for all  $\gamma > 0$  and  $(\alpha, \beta) \in \mathcal{R}(P, Q)$

$$\alpha - \gamma\beta \leq P \left( \left\{ \log \frac{dP}{dQ} > \log \gamma \right\} \right)$$

$$\beta - \frac{\alpha}{\gamma} \leq Q \left( \left\{ \log \frac{dP}{dQ} < \log \gamma \right\} \right)$$

## Neyman–Pearson Lemma

Define the **log-likelihood ratio** (LLR),

$$L(\omega) = \log \frac{dP}{dQ}(\omega)$$

For any  $\alpha$ ,  $\beta_\alpha(P, Q)$  is achieved by the **LLR test**

$$P_{Z|\omega}(\{0\}|\omega) = \begin{cases} 1 & L(\omega) > \tau \\ \lambda & L(\omega) = \tau \\ 0 & L(\omega) < \tau \end{cases}$$

where  $\tau$  and  $\lambda \in [0, 1]$  solve

$$\alpha = P(\{L > \tau\}) + \lambda P(\{L = \tau\})$$

$\Rightarrow L(\omega)$  is a sufficient statistic for  $\{H_i\}$

$\Rightarrow \mathcal{R}(P, Q)$  is closed and convex, and

$$\mathcal{R}(P, Q) = \{(\alpha, \beta) : \beta_\alpha(P, Q) \leq \beta \leq 1 - \beta_{1-\alpha}(P, Q)\}$$

We have implicitly assumed  $P \ll Q$  (and  $Q \ll P$ ), if this is not the case we can define  $F = \cup\{A \in \mathcal{A} : Q(A) = 0 \text{ while } P(A) > 0\}$

Then set  $P_{Z|\omega}(\{0\}|\omega) = 1$  on  $F$  and use the LLR test on  $F^c$

In the extreme  $P(F) = 1$  we can set  $P_{Z|\omega}(\{0\}|\omega) = 1$  on  $F$  and  $P_{Z|\omega}(\{0\}|\omega) = 0$  on  $F^c$ , to get

$$\alpha = P(F) = 1 \quad \text{and} \quad \beta = Q(F) = 0$$

the test is **singular**,  $P \perp Q$

## Proof of optimality

Let  $g(\omega) = P_{Z|\omega}(\{0\}|\omega)$  for any  $P_{Z|\omega}$  such that  $E_P[g(\omega)] \geq \alpha$

Let

$$f(\omega) = \begin{cases} 1 & L(\omega) > \tau \\ \lambda & L(\omega) = \tau \\ 0 & L(\omega) < \tau \end{cases}$$

and  $t = \exp(\tau)$ , where  $\tau$  and  $\lambda$  are chosen so that  $\alpha = E_P[f(\omega)]$

Note that

$$(f(\omega) - g(\omega)) \left( \frac{dP}{dQ}(\omega) - t \right) \geq 0$$

Hence

$$t \int (f - g) dQ \leq \int (f - g) dP \leq 0$$

$$\Rightarrow E_Q[g(\omega)] \geq E_Q[f(\omega)]$$

With probabilities on  $\{H_i\}$ :  $\Pr(H_1 \text{ true}) = p$ ,  $\Pr(H_0 \text{ true}) = 1 - p$

Let  $g(\omega) = P_{Z|\omega}(\{0\}|\omega)$ , then the **average probability of error**

$$\begin{aligned} P_e &= (1 - p) \left( 1 - \int g(\omega) dP \right) + p \int g(\omega) dQ \\ &= \int g(\omega) \left( p - (1 - p) \frac{dP}{dQ}(\omega) \right) dQ + 1 - p \end{aligned}$$

Thus the LLR test is optimal also for minimizing  $P_e$ , with

$$\tau = \log \frac{p}{1 - p}$$

and with  $\lambda \in [0, 1]$  arbitrary (e.g.  $\lambda = 1 - p$ )

For the total variation between  $P$  and  $Q$ , we have

$$\begin{aligned} \text{TV}(P, Q) &= \sup_{E \in \mathcal{A}} (P(E) - Q(E)) \\ &= \sup_{E \in \mathcal{A}} \left\{ \int_E \left( \frac{dP}{dQ}(\omega) - 1 \right) dQ \right\} \end{aligned}$$

achieved by  $E = \{\omega : L(\omega) > 0\}$  (if  $P \ll Q$ )

Thus for the LLR test that minimizes  $P_e$  with  $p = 1/2 \Rightarrow \tau = 0$  (and using  $\lambda = 0$ ),

$$\begin{aligned} \text{TV}(P, Q) &= P(\{L(\omega) > 0\}) - Q(\{L(\omega) > 0\}) \\ &= \alpha - \beta_\alpha(P, Q) = 1 - 2P_e \end{aligned}$$

$$\Rightarrow P_e = (1 - \text{TV}(P, Q))/2$$

For  $P \perp Q$ ,  $E = F = \cup\{A \in \mathcal{A} : Q(A) = 0 \text{ while } P(A) > 0\}$ ,

$$\text{TV}(P, Q) = P(F) - Q(F) = 1 \quad \text{and} \quad P_e = 0$$

## General Decision Theory

Given  $(\Omega, \mathcal{A}, P)$  and assume  $(E, \mathcal{E})$  is a standard Borel space (i.e., there is a topology  $\mathcal{T}$  on  $E$ ,  $(E, \mathcal{T})$  is Polish, and  $\mathcal{E} = \sigma(\mathcal{T})$ )

$X : \Omega \rightarrow E$  is measurable if  $\{\omega : f(\omega) \in F\} \in \mathcal{A}$  for all  $F \in \mathcal{E}$

A measurable  $X$  is a random

- variable if  $(E, \mathcal{E}) = (\mathbb{R}, \mathcal{B})$
- vector if  $(E, \mathcal{E}) = (\mathbb{R}^n, \mathcal{B}^n)$
- sequence if  $(E, \mathcal{E}) = (\mathbb{R}^\infty, \mathcal{B}^\infty)$
- **object** in general

Let  $T$  be arbitrary, but typically  $T = \mathbb{R}$

Denote  $E^T = \{\text{functions from } T \text{ to } E\}$ , then  $X$  is a random

- **process** if  $(E, \mathcal{E}) = (\mathbb{R}^T, \mathcal{B}^T)$

Given  $(\Omega, \mathcal{A}, P)$ ,  $(E, \mathcal{E})$  and  $X : \Omega \rightarrow E$  measurable

For a general **parameter set**  $\Theta$  let  $\mathcal{P} = \{P_\theta : \theta \in \Theta\}$  be a set of possible distributions for  $X$  on  $(E, \mathcal{E})$

Assume we observe  $X \sim P_\theta$  (i.e.  $P_\theta$  is the correct distribution), and we are interested in knowing  $T(\theta)$ , for some  $T : \Theta \rightarrow F$

A **decision rule** is a kernel  $P_{\hat{T}|X=x}$  such that  $P_{\hat{T}} = P_{\hat{T}|X} \circ P_X$  on  $(\hat{F}, \hat{\mathcal{F}})$  (for  $(\hat{F}, \hat{\mathcal{F}})$  standard Borel, typically  $\hat{F} = F = \mathbb{R}$  and  $\hat{\mathcal{F}} = \mathcal{B}$ )

Define a **loss function**  $\ell : F \times \hat{F} \rightarrow \mathbb{R}$  and the corresponding **risk**

$$R_\theta(\hat{T}) = \int \left\{ \int \ell(T(\theta), \hat{T}) dP_{\hat{T}|X=x} \right\} dP_\theta = E_\theta[\ell(T, \hat{T})]$$

## Bayes Risk

Assume  $\Theta = \mathbb{R}$  and  $T(\theta) = \theta$  (for simplicity)

Postulate a **prior distribution**  $\pi$  for  $\theta$  on  $(\mathbb{R}, \mathcal{B})$

The **average risk**

$$R_\pi(\hat{\theta}) = \int R_\theta(\hat{\theta}) d\pi = \int \left\{ \int \ell(\theta, \hat{\theta}) d(P_{\hat{\theta}|X} \circ P_\theta) \right\} d\pi$$

and the **Bayes risk**

$$R_\pi^* = \inf_{P_{\hat{\theta}|X}} R_\pi(\hat{\theta})$$

achieved by the **Bayes estimator**  $P_{\hat{\theta}|X=x}^*$

Define  $P_{\theta|X}$  from  $\pi = P_{\theta|X} \circ P_{\theta}$ , then since  $\theta \rightarrow X \rightarrow \hat{\theta}$

$$\begin{aligned} E_{\pi} \left[ \int \left\{ \int \ell(\theta, \hat{\theta}) dP_{\hat{\theta}|X=x} \right\} dP_{\theta} \right] \\ = \int \left\{ \int \left\{ \int \ell(\theta, \hat{\theta}) dP_{\hat{\theta}|X=x} \right\} dP_{\theta|X=x} \right\} d(P_{\theta} \circ \pi) \end{aligned}$$

Hence we can define  $\hat{\theta}(x)$  via  $\ell(\theta, \hat{\theta}(x)) = \int \ell(\theta, \hat{\theta}) dP_{\hat{\theta}|X=x}$  and for each  $X = x$  minimize

$$\int \ell(\theta, \hat{\theta}(x)) dP_{\theta|X=x}$$

$\Rightarrow$  the Bayes estimator is always **deterministic**

- Thus we can always work with  $\hat{\theta}(x)$  instead of  $P_{\hat{\theta}|X}$
- Can also be proved more formally from the fact that  $R_{\pi}(\hat{\theta})$  is linear in  $P_{\hat{\theta}|X}$  and the set  $\{P_{\hat{\theta}|X}\}$  is convex

## Data processing inequality

Given a prior distribution  $\pi$  for  $\theta$ , assume that

$$\theta \rightarrow X \rightarrow Y$$

and let  $R_{\pi}^*(X)$  denote the Bayes risk based on observing  $X$ , and similarly  $R_{\pi}^*(Y)$  based on  $Y$ . Then

$$R_{\pi}^*(X) \leq R_{\pi}^*(Y)$$

**Proof** Define

$$f(x, u) = \sup\{v \in [0, 1] : P_{Y|X=x}([0, v]) < u\}$$

Let  $U \sim \mathcal{U}([0, 1])$  and independent of  $X$ , then  $f(x, U) \sim P_{Y|X=x}$  and

$$\begin{aligned} R_{\pi}^*(X) &= \inf_{\hat{\theta}(\cdot)} E[\ell(\theta, \hat{\theta}(X))] \leq \inf_{u \in [0, 1]} E[\ell(\theta, \tilde{\theta}(f(X, u)))] \\ &\leq E[\ell(\theta, \tilde{\theta}(f(X, U)))] = E[\ell(\theta, \tilde{\theta}(Y))] = R_{\pi}^*(Y) \end{aligned}$$

where  $\tilde{\theta}(Y)$  is the Bayes estimator based on  $Y$ .

# Minimax Risk

Let

$$R^* = \inf_{P_{\hat{\theta}|X}} \sup_{\theta \in \Theta} R_{\theta}(\hat{\theta}) = \inf_{P_{\hat{\theta}|X}} \sup_{\theta \in \Theta} \int \left\{ \int \ell(\theta, \hat{\theta}) dP_{\hat{\theta}|X=x} \right\} dP_{\theta}$$

denote the **minimax risk**

The problem is convex, and we can write

$$R^* = \inf t \quad \text{s.t.} \quad E_{\theta}[\ell(\theta, \hat{\theta})] \leq t \quad \text{for all } \theta \in \Theta$$

over  $P_{\hat{\theta}|X}$  and  $t$

Assuming  $\Theta$  is finite for simplicity, we get the Lagrangian

$$L(P_{\hat{\theta}|X}, t, \{\lambda(\theta)\}) = t + \sum_{\theta} \lambda(\theta) (E_{\theta}[\ell(\theta, \hat{\theta})] - t)$$

and the dual function  $g(\{\lambda(\theta)\}) = \inf_{P_{\hat{\theta}|X}, t} L(P_{\hat{\theta}|X}, t, \{\lambda(\theta)\})$

Note that unless  $\sum_{\theta} \lambda(\theta) = 1$ , we get  $g(\{\lambda(\theta)\}) = -\infty$

Thus  $\sup g(\{\lambda(\theta)\})$  is attained for  $\lambda(\theta) =$  a pmf on  $\theta$ , and

$$\sup_{\{\lambda(\theta)\}} g(\{\lambda(\theta)\}) = \sup_{\{\lambda(\theta)\}} \inf_{P_{\hat{\theta}|X}} \sum_{\theta} \lambda(\theta) E_{\theta}[\ell(\theta, \hat{\theta})] = \sup_{\pi} R_{\pi}^*$$

with  $\pi(\theta) = \lambda(\theta)$  is the **worst-case Bayes risk**



Because of weak duality, we always have

$$\sup_{\pi} R_{\pi}^* \leq R^*$$

and **strong duality**, i.e.

$$R^* = \sup_{\pi} R_{\pi}^*$$

holds if

- $\theta$  is finite and  $\mathcal{X}$  is finite, or
- $\theta$  is finite and  $\inf_{\theta, \hat{\theta}} \ell(\theta, \hat{\theta}) > -\infty$

and also under very general conditions (see [PW:28.3.4]. . . )

We have thus established the **minimax theorem**

When strong duality holds the minimax risk is obtained by a deterministic  $\hat{\theta}(x)$